

A scanning electron microscope (SEM) image of a microelectromechanical system (MEMS) device. The device features a central vertical structure with a complex, multi-faceted top section. Below this central structure are two large, rounded rectangular pads. The background is a textured, light gray surface. The image is presented in grayscale with a yellow border.

# MEMS Research at NISRC

400µm

3.7KV

73

042

R

# Microelectromechanical Systems (MEMS)

*MEMS* are miniaturised components or devices.  
They may be Electrical, Mechanical or Fluidic.

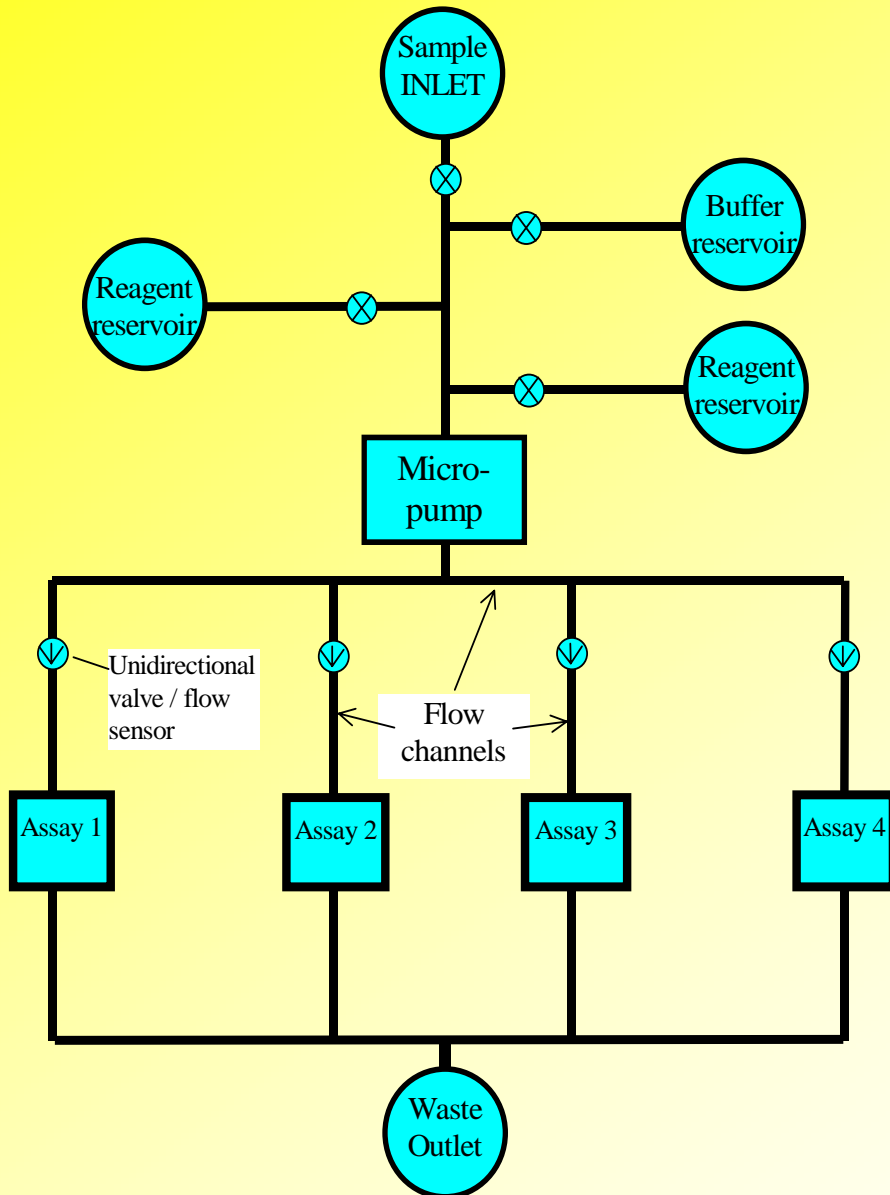
Applications :- Sensors ; Actuators

Examples :- Pressure Sensors, Accelerometers, Position Detectors, Micromotors, Chemical Microlabs.  
Microfluidics, pumps, valves.

## Micromachining

Micromachining is a set of processes that enables fabrication of *MEMS* devices which includes bulk or surface machining techniques.

# Microfluidic Systems

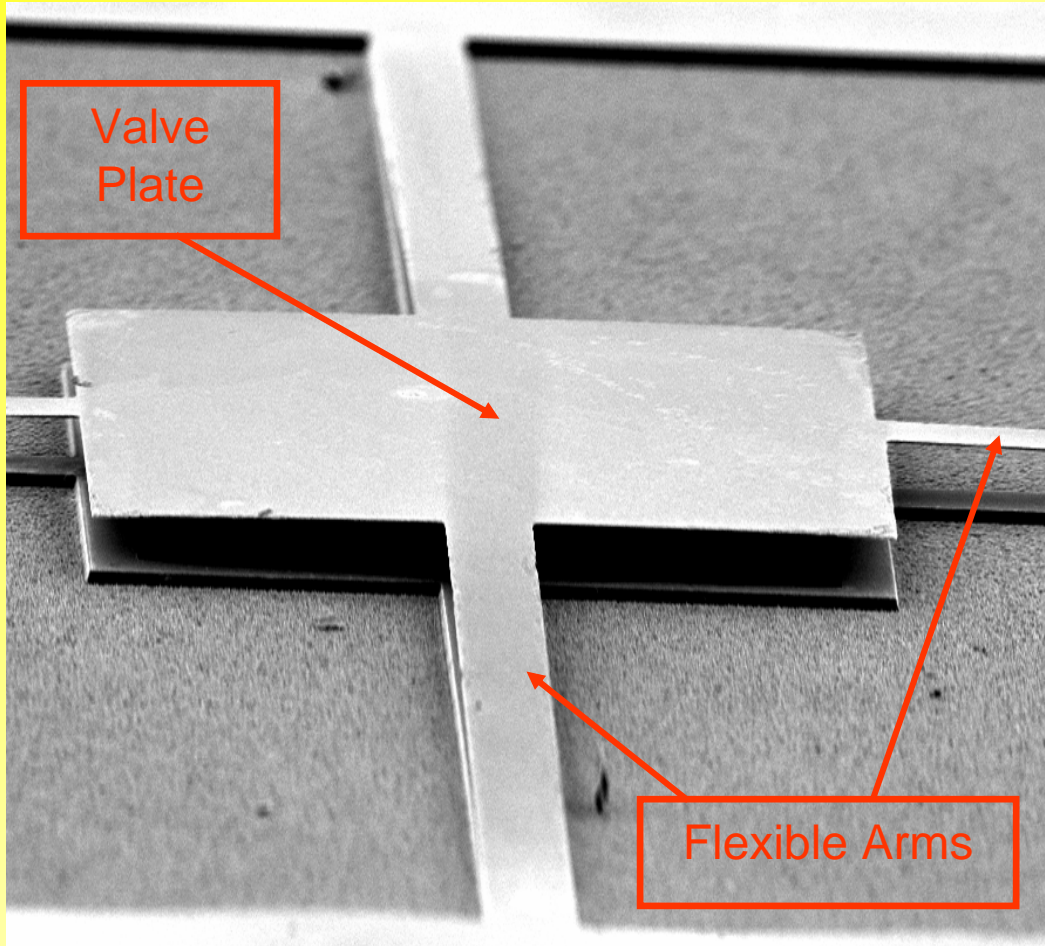


- ❖ Integrated chemical analysis.
- ❖ “Lab-on-a-chip”
- ❖ Chemical micro-analysers.
- ❖ Chemical micro-synthesis.

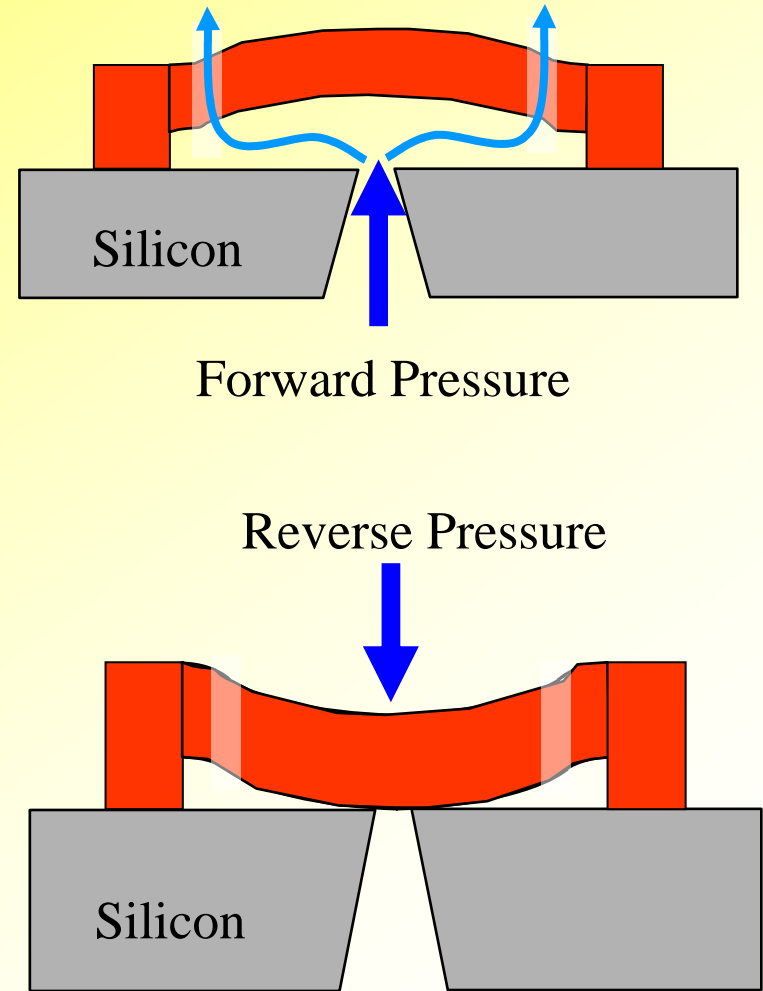
## Advantages

- ❖ Low reagent & sample volumes.
- ❖ Fast analysis.
- ❖ Portable.
- ❖ High surface area to volume ratio.
- ❖ Good Heat transfer.

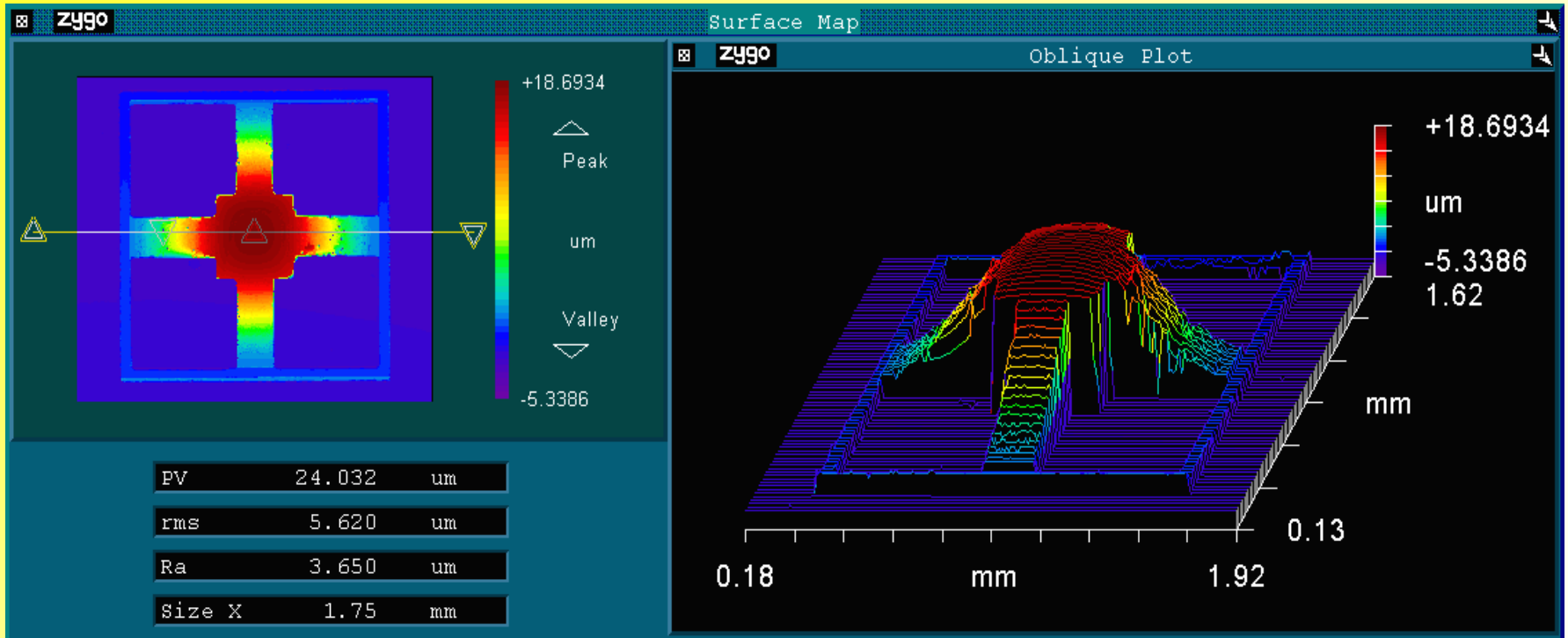
# Polysilicon Micro-valves



Electron Microscope Image



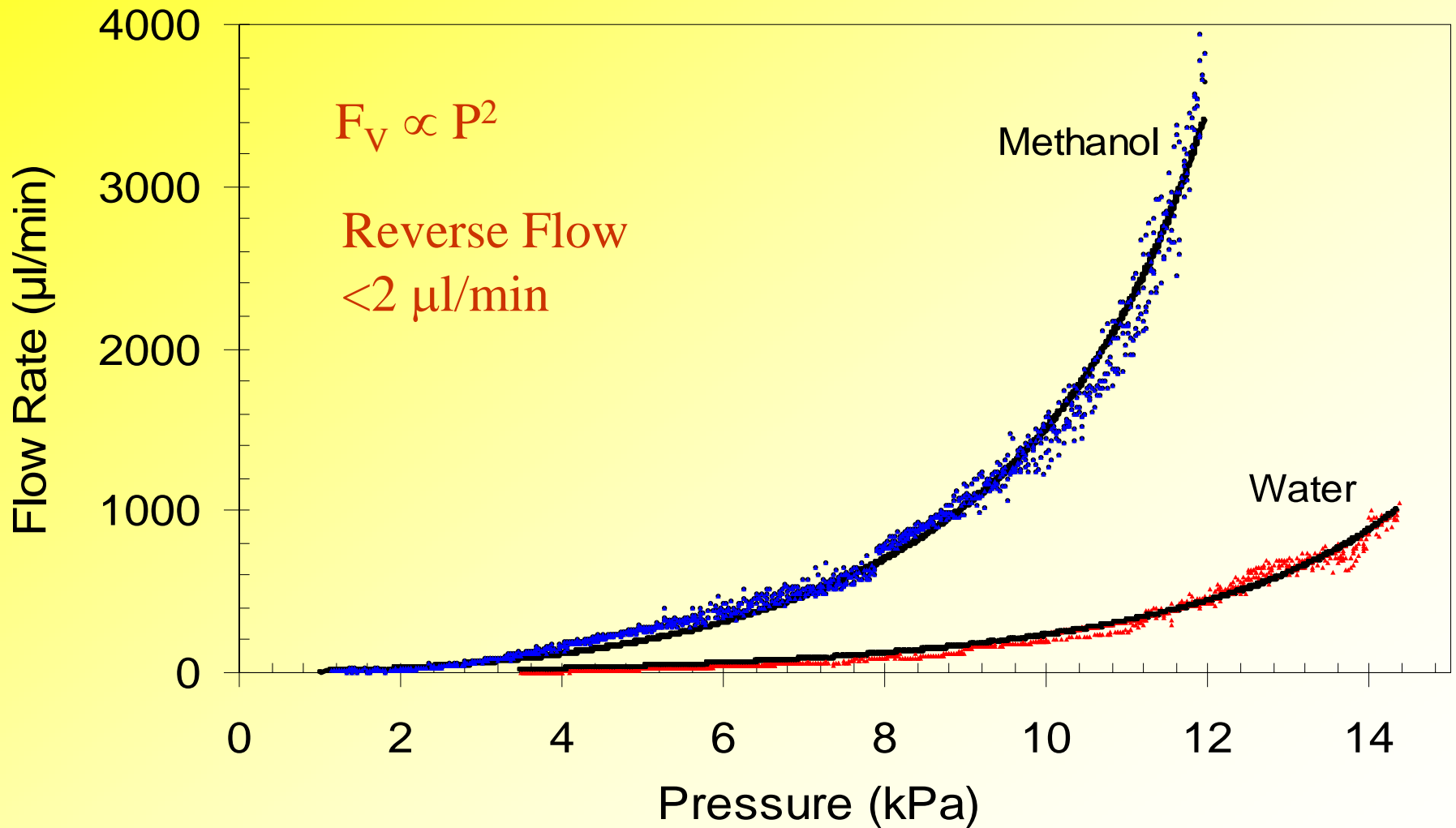
# Surface profile of microvalve.



**Surface view of relaxed microvalve measured using a ZYGO optical profile instrument.**

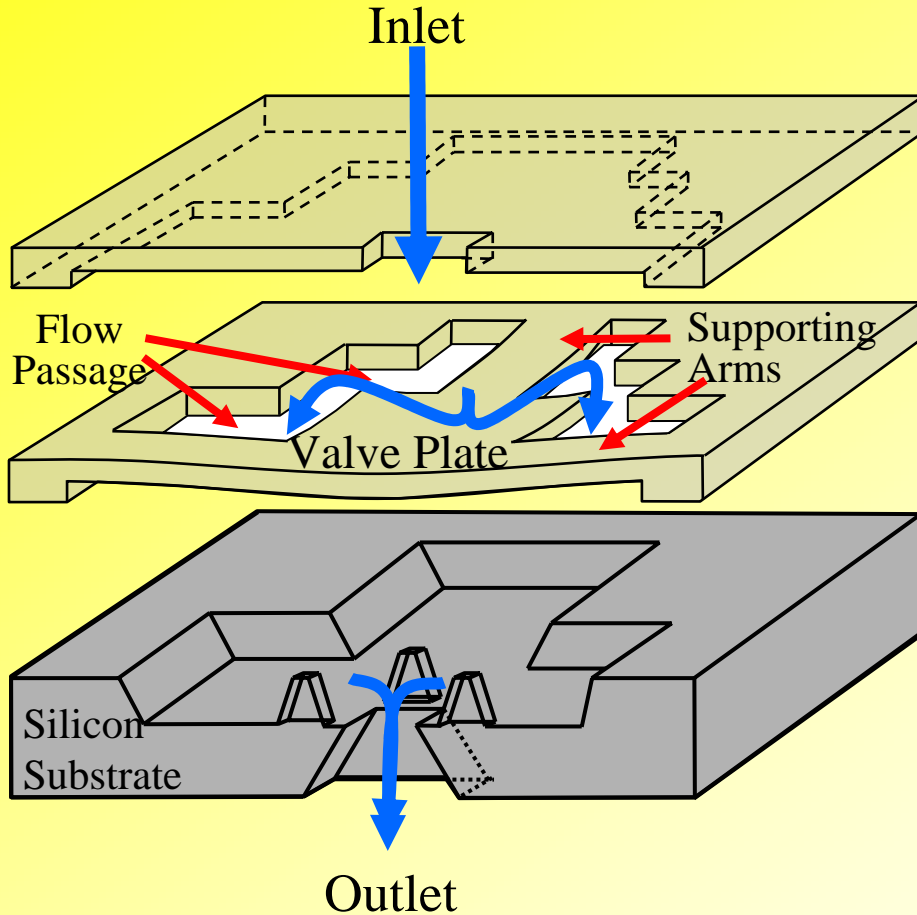
**Compressive stress in polysilicon ~ 120MPa**

# Microvalve Forward Flow Results



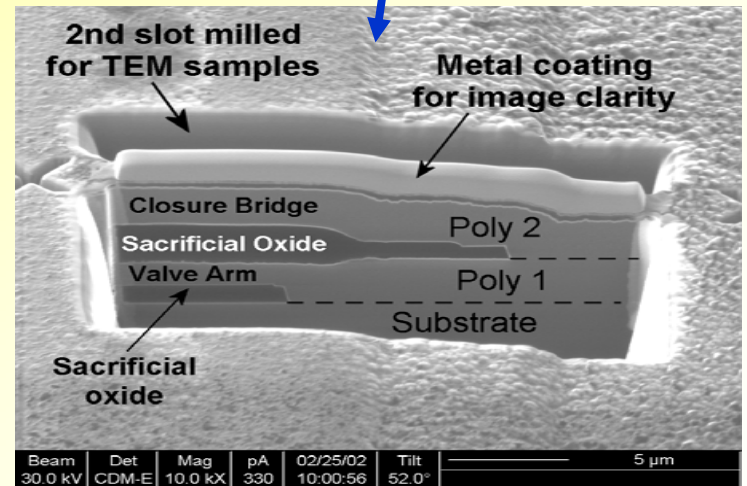
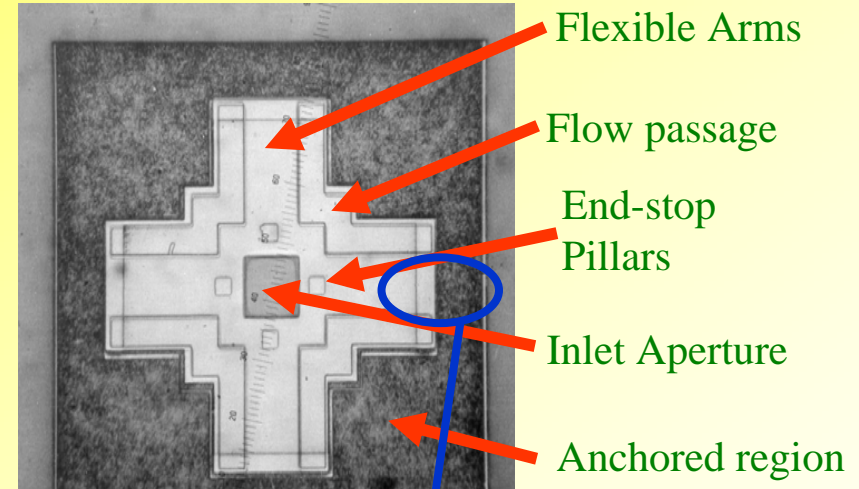
**Valve dimensions : 400 μm arm length.  
100 μm square inlet hole.**

# Stacked Microvalve



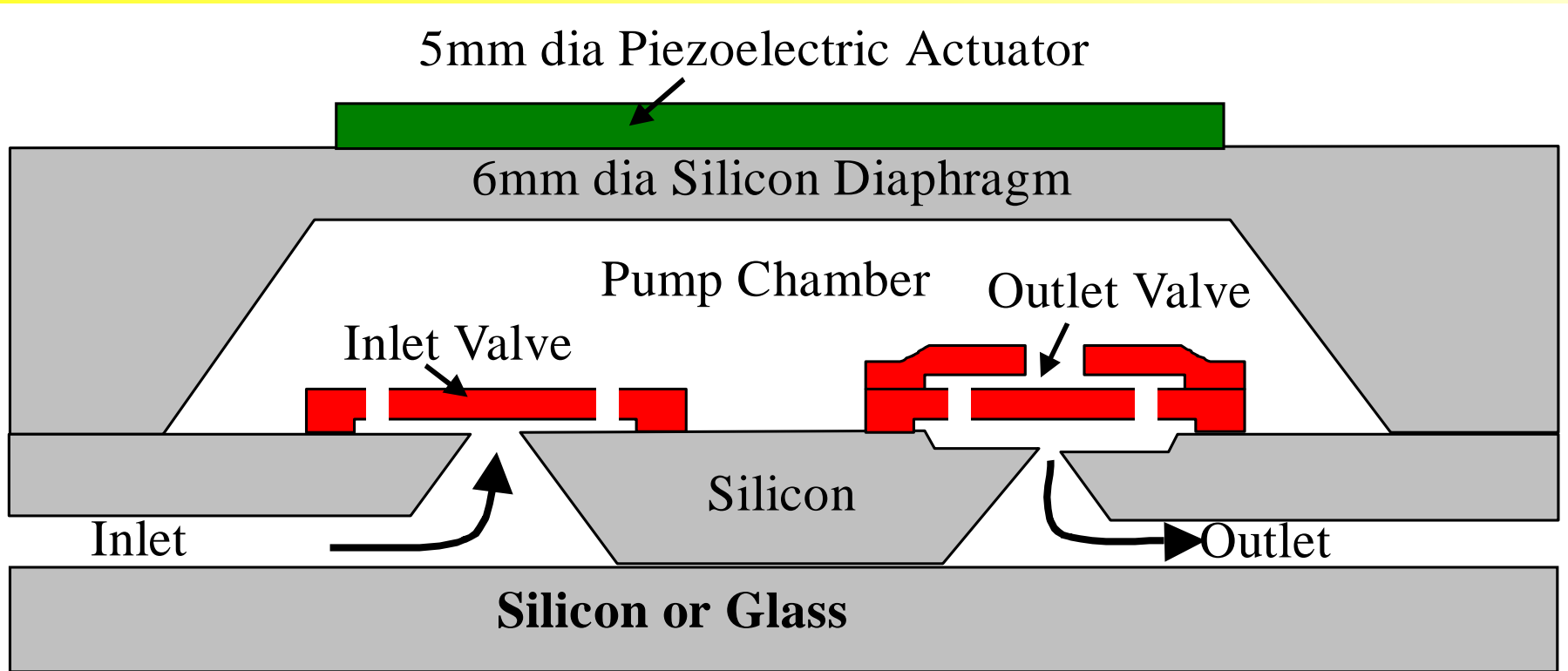
**Fluid Flow under Forward Pressure**

**Overall dimensions 1.2mm square**



**Surface and Cross Sectional View Across Arm**

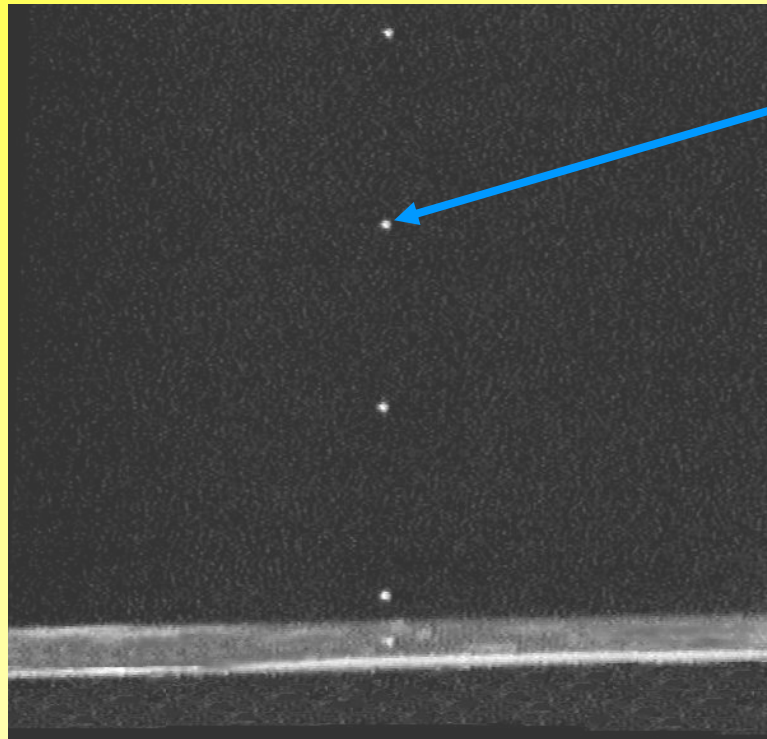
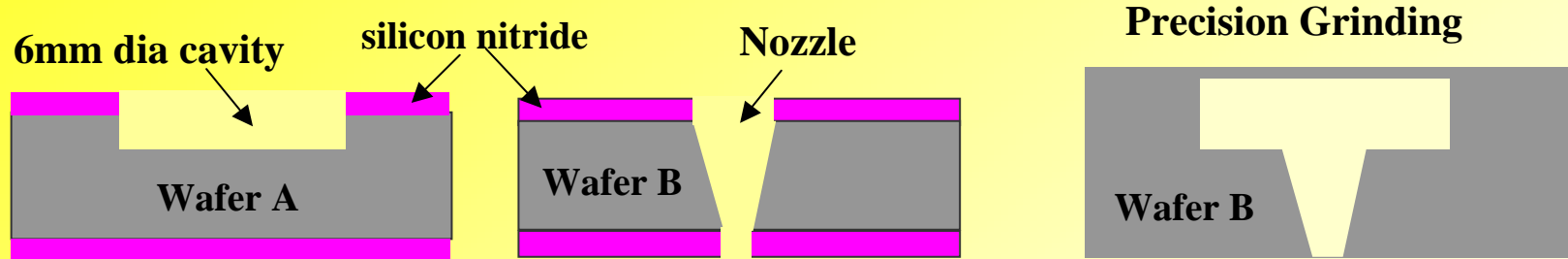
# Piezo-electrically Actuated Micropump



**Micromachined pump incorporating the stacked microvalve.**

**Pump rate at 5Hz:-  $0.5\mu\text{l}/\text{min}$**

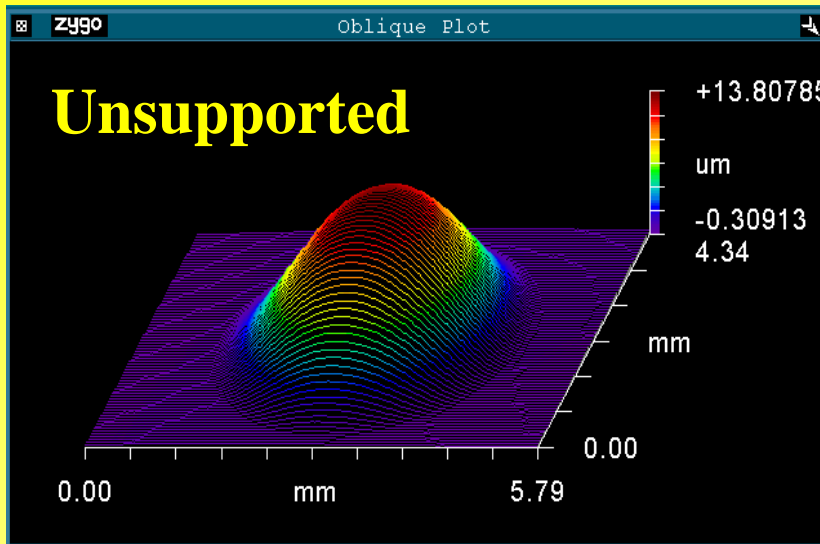
# Nano-litre Dispensers



Droplets ejected from a dispenser using piezoelectric actuation.

Droplet volume: 0.3 – 10nl;  
depending on device dimensions  
and driving signals.

# Diaphragm Distortion



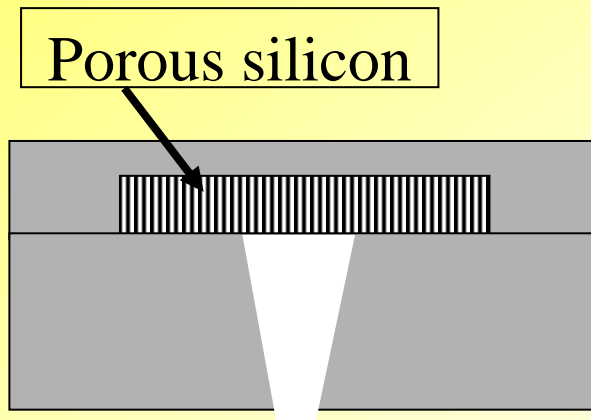
Diaphragms produced by grinding without support exhibit convex distortion.

Support can be provided by forming sacrificial porous silicon in the region where the cavity is to be formed.

Deflection during grinding is reduced and post grind distortion minimised.

After grinding, the porous silicon can be selectively etched.

Distortion is suppressed by a factor of up to 300.



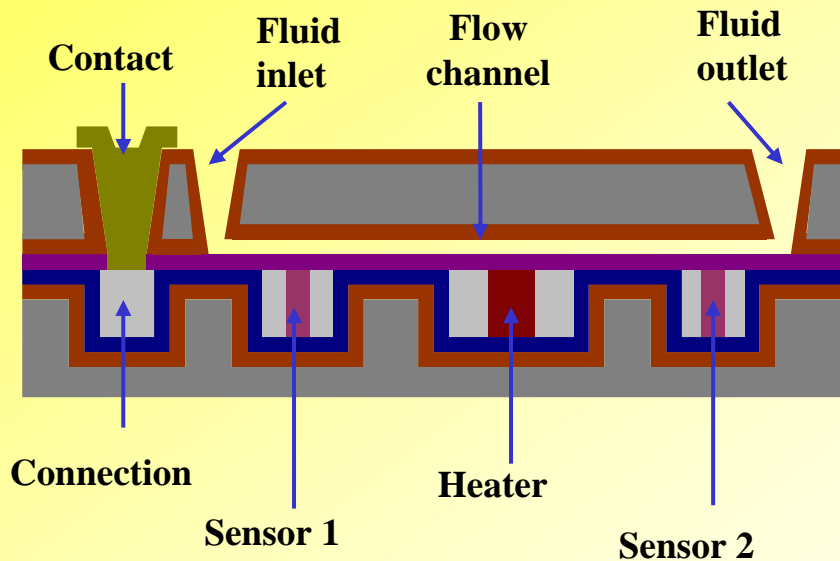
# Integrated microfluidic flow sensor

Heat transfer used to determine flow rate.

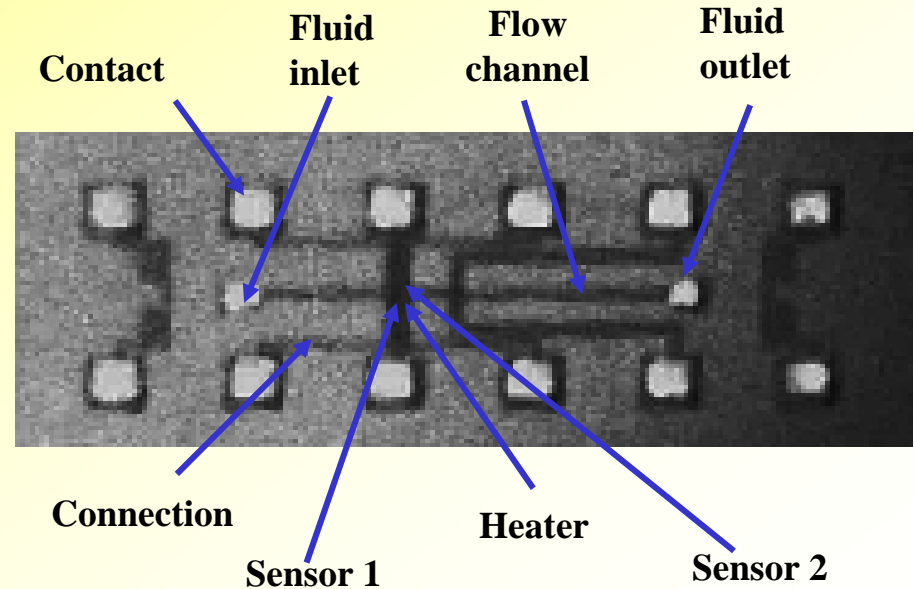
Polysilicon resistors – high thermal coefficient of resistance.

Resistance difference between sensors 1 & 2 increases with flow.

Cross-sectional view

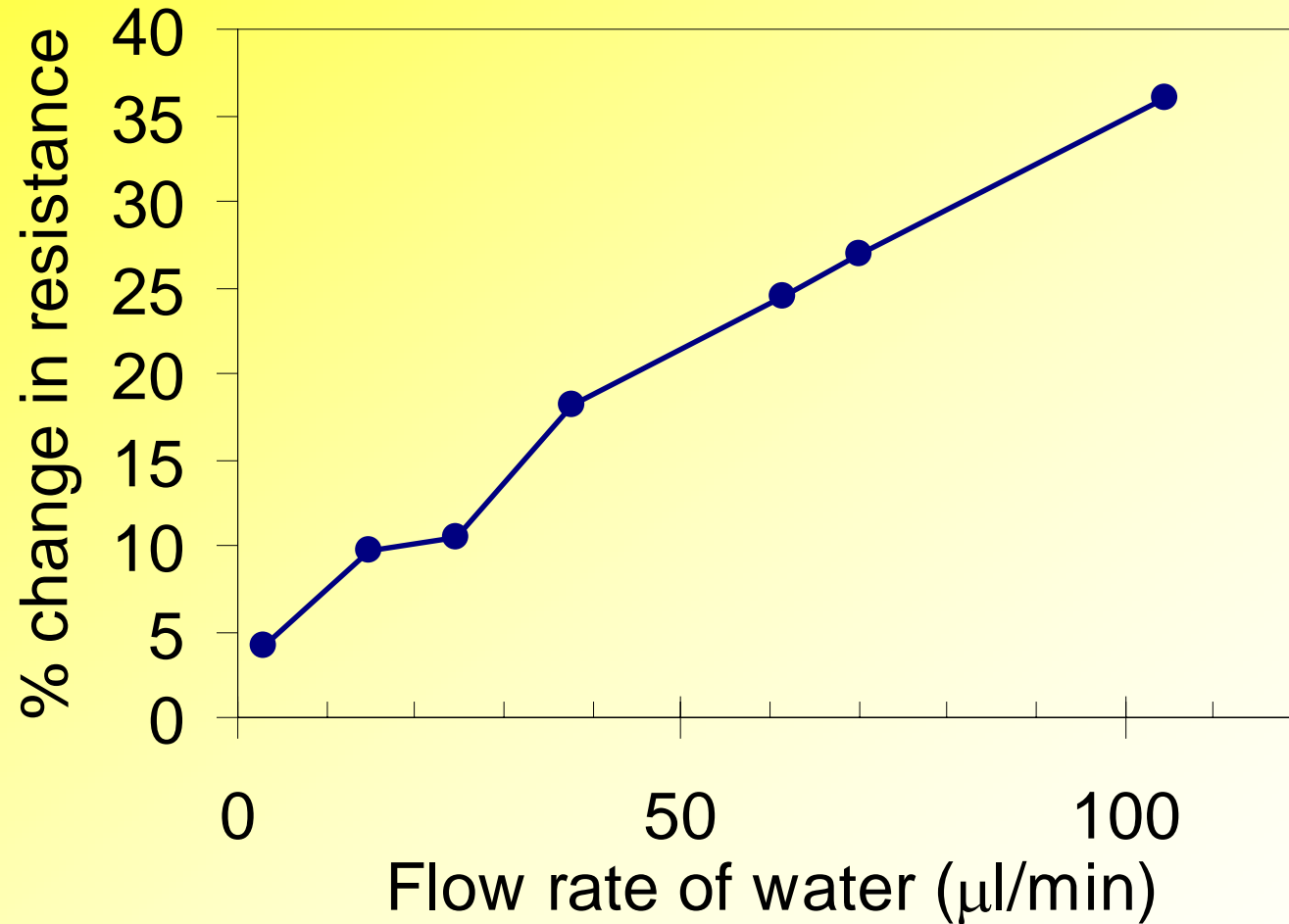


Plan view – optical micrograph



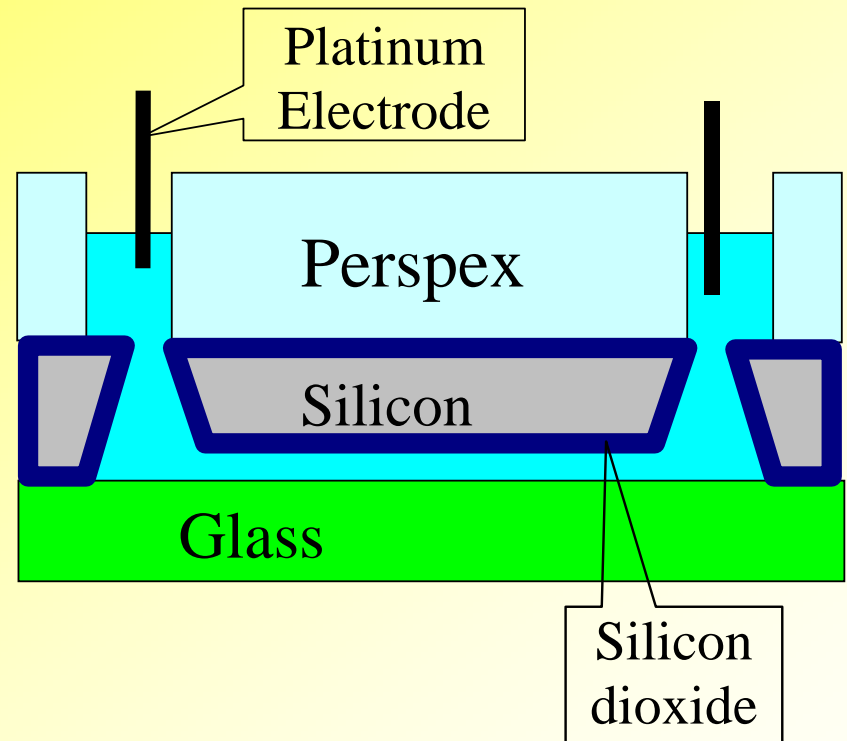
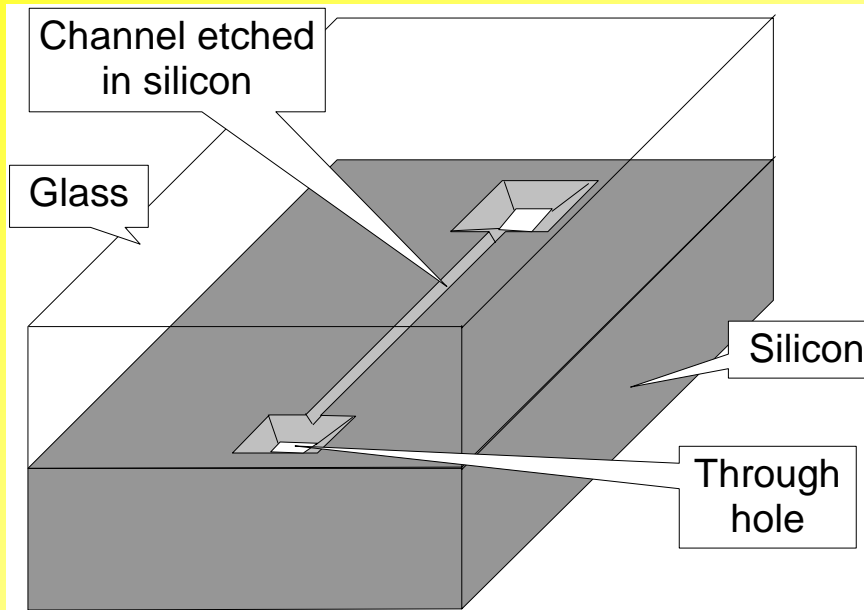
100 $\mu$ m wide, 10-20 $\mu$ m long resistors.

# Polysilicon Resistor Temperature Sensors



Single resistor as 'hot-wire' anemometer.

# Electro-osmotic pumping - Test structure



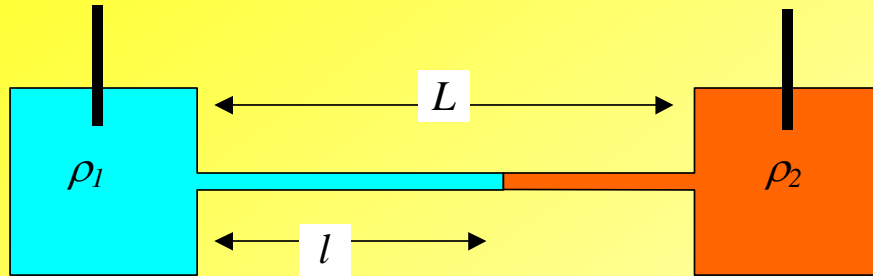
- **75-100 $\mu\text{m}$  wide, 9mm long channels.**
- **Oxidised channels in silicon bonded to glass.**
- **Through-etched inlet/outlet holes.**
- **Glued perspex reservoirs.**
- **Platinum wire driving electrodes.**

# Electro-osmotic Pumping

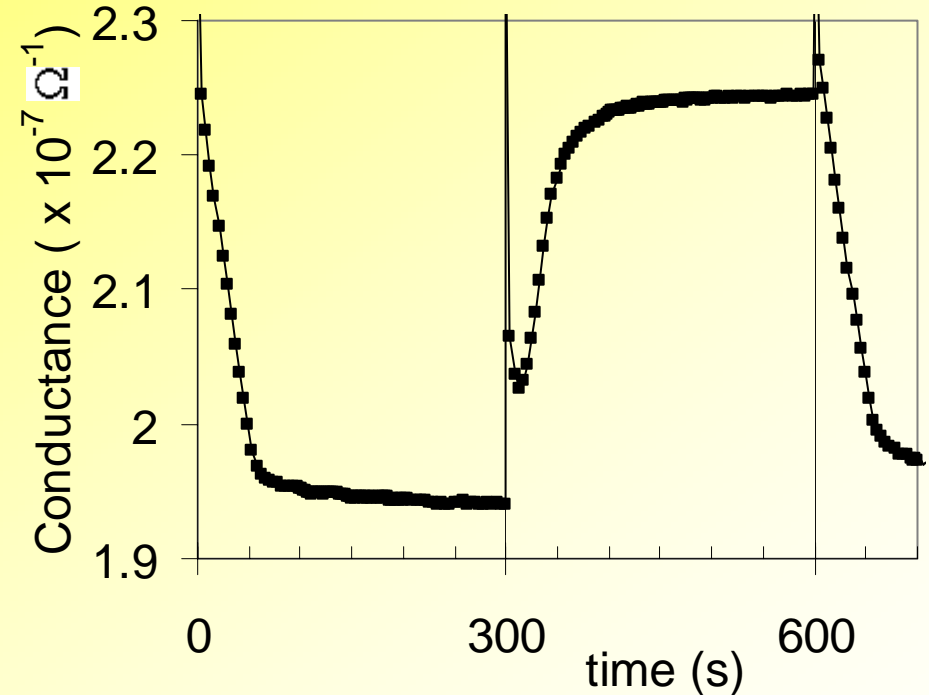


**Liquid being electrically ‘pumped’ along a  $100\mu\text{m}$  wide pipe fabricated in the surface of a silicon wafer.**

# Conductivity Monitoring in Silicon Channel.



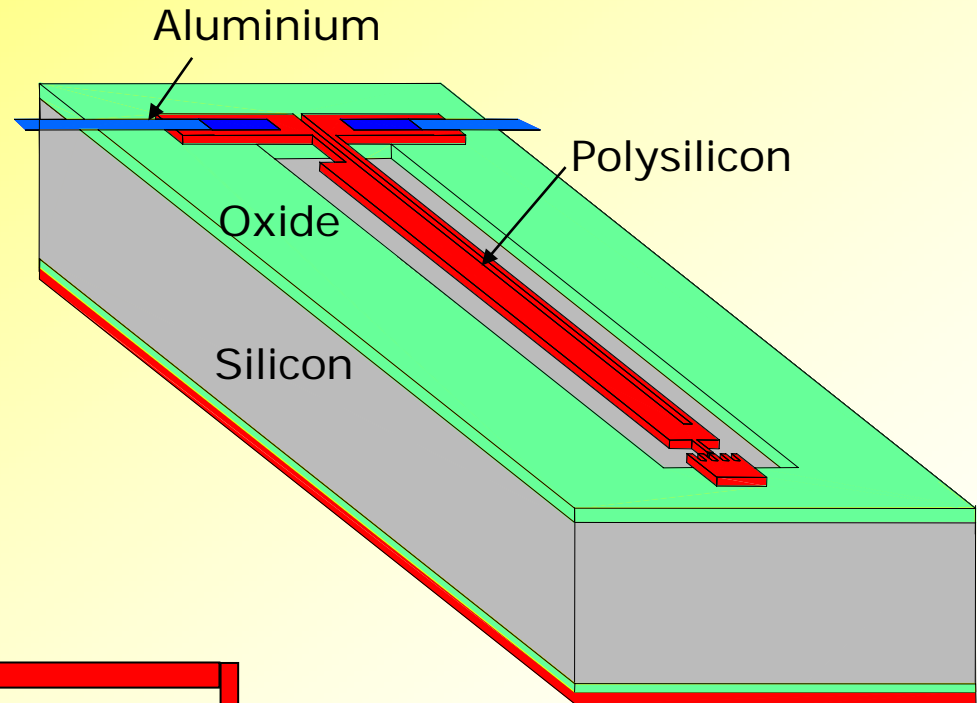
- Flow rates can be determined by monitoring conductance in the channel when two liquids of different conductivity are present.



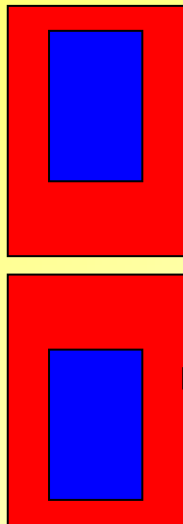
Flow velocity 0.16 - 0.23 mm/s,  
in 9mm long, 75 $\mu$ m wide channel  
at 100V. ( $\sim 25$ nl/min)

# Electrothermal Actuator

**Mechanical actuation via resistive Joule heating of polysilicon cantilever beams**



**Contact pads**



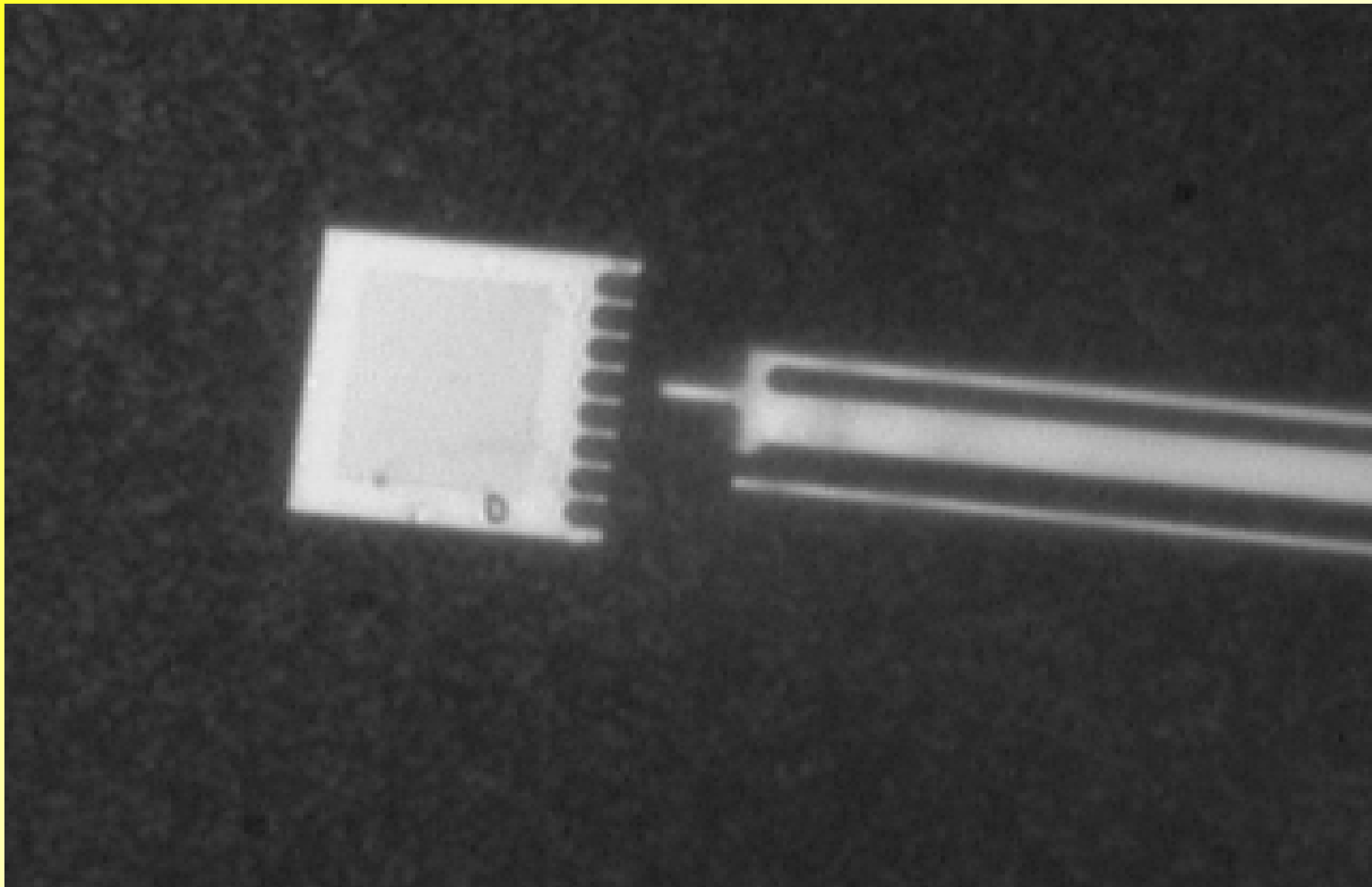
**Hot arm**

**Cold arm**

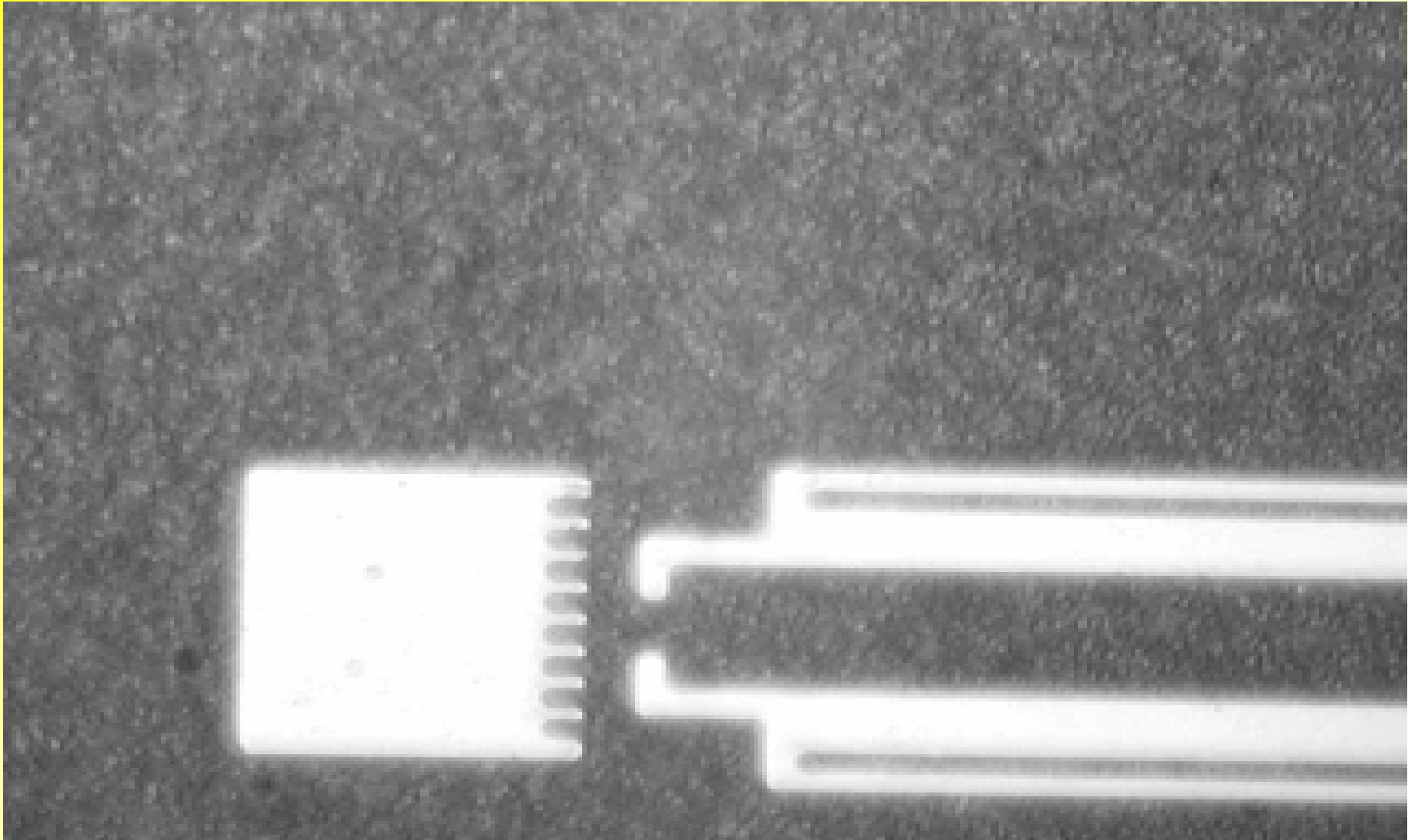
**Simple Cantilever Beam Structure for Force Measurement**

**Gary O'Neill – MEng. Project Student**

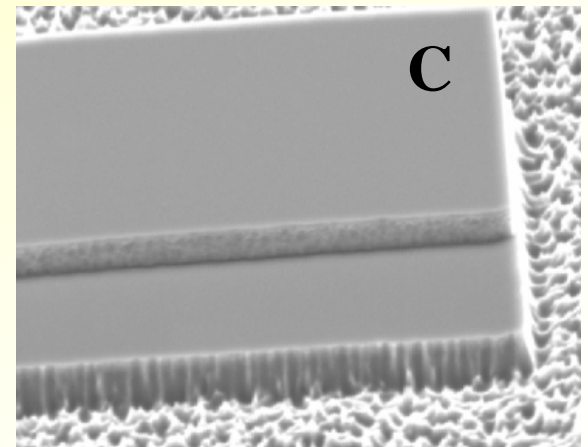
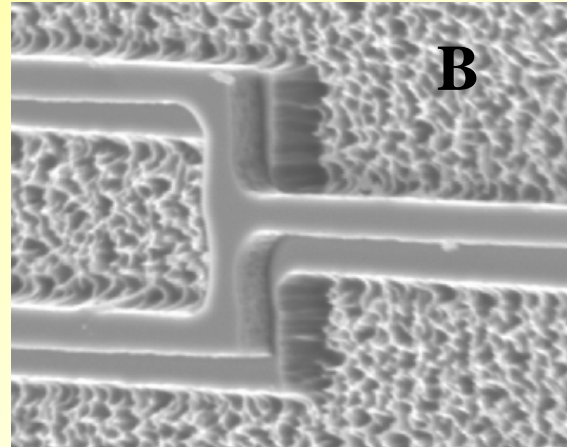
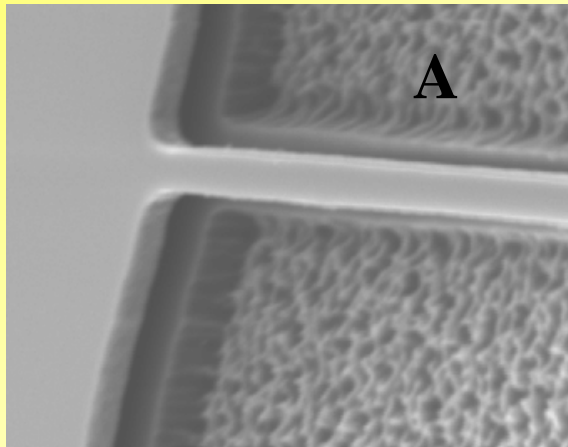
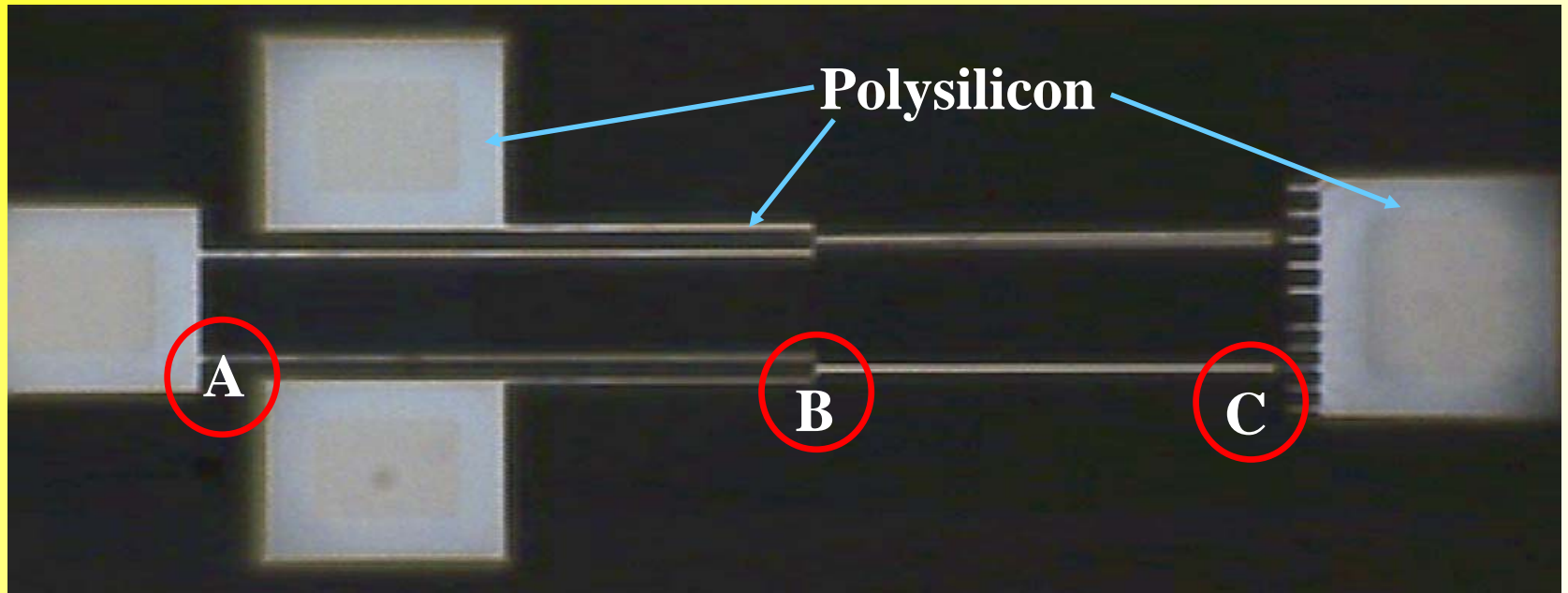
# Electrothermal Actuator



# Polysilicon Micro-Tweezers



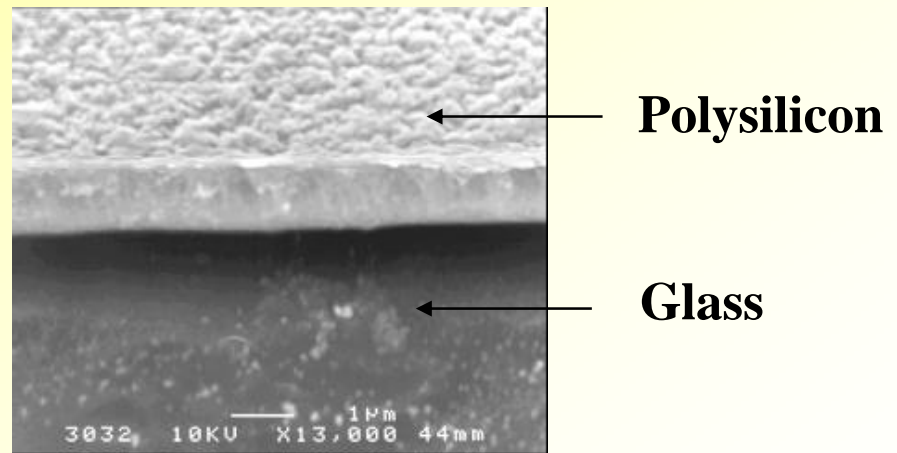
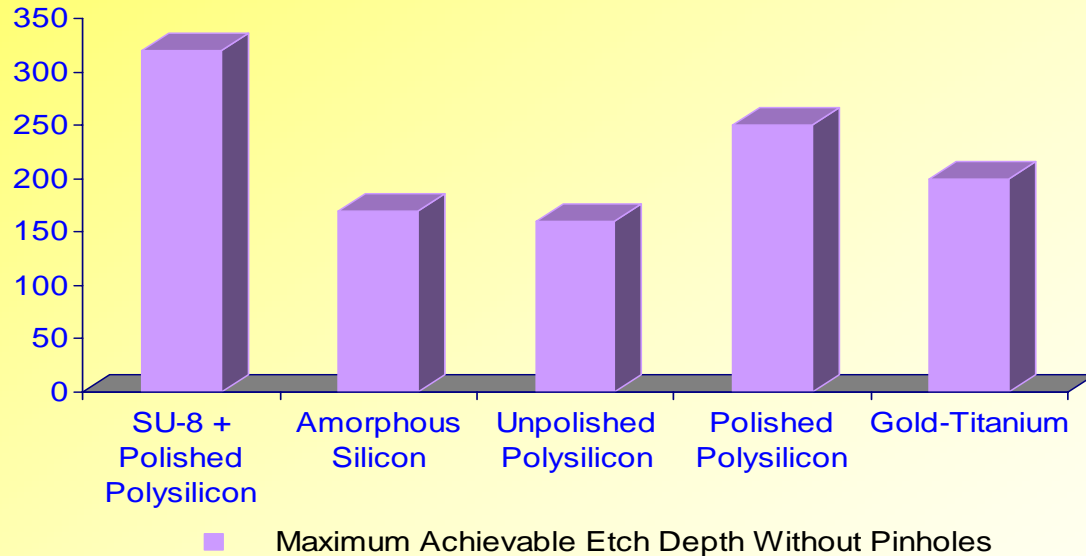
# Polysilicon Cantilever Strain Gauge



# Deep Wet Etching of Glass

➤ In many areas of MEMS, glass is an attractive alternative substrate to silicon due to its optical properties, chemical inertness and relative cost.

➤ For deep wet etching, using HF-based solutions, the challenge is to find a suitable masking layer.



“Characterisation of masking materials for deep glass micromachining”, D.C.S. Bien, P.V.Rainey, S.J.N.Mitchell, H.S.Gamble, *Journal of Micromechanics and Microengineering*, Vol.13, No.4, July 2003, ppS34

# Silicon Micromachining

## ➤ Anodic Bonding.

- Silicon to Glass
- Silicon Dioxide to Glass
- Silicon Nitride to Glass.

## ➤ Silicon Direct Bonding.

- Silicon to Silicon
- Silicon Dioxide to Silicon
- Silicon Nitride to Silicon.

## ➤ Aligned Silicon Bonding.

## ➤ Double-Sided Photolithography.

## ➤ Precision Grinding.

## ➤ Thick-film Piezoelectrics.

## ➤ Porous Silicon.

## ➤ Thick Photoresist (SU-8).

## ➤ Polyamide.